

LSDS-IR: LARGE-SCALE AND DISTRIBUTED SYSTEMS FOR INFORMATION RETRIEVAL

2013 EDITION OF THE WORKSHOP IS CO-LOCATED AT ACM WSDM 2013

9:00-09:10	Welcome and Opening
09:10-10:10	Invited Talk: Analyzing the performance of top-k retrieval algorithms Marcus Fontoura
10:10-10:40	Retrieval of Highly Dynamic Information in an Unstructured Peer-to-Peer Network H. Asthana and Ingemar Cox.
10:40-11:00	Coffee break
	Digital Libraries & Archives
11:00-11:30	Scalability Bottlenecks of the CiteSeerX Digital Library Search Engine Jian Wu, Pradeep Teregowda, Eric Treece, Madian Khabza, Douglas Jordan, Stephen Carman, Prasenjit Mitra and C. Lee Giles.
11:30-12:00	A Supervised Learning Method for Context-Aware Citation Recommendation in a Large Corpus Lior Rokach.
12:00-12:30	User-Defined Redundancy in Web Archives Bibek Paudel, Avishek Anand and Klaus Berberich.
12:30-13:00	Metric Suffix Array For Large-Scale Similarity Search Hisham Mohamed and Stéphane Marchand-Maillet.
13:00-14:30	Lunch break
14:30-15:30	Invited Talk: Quasi-succinct indices Sebastiano Vigna
15:30-16:00	Efficient Weighted Histogramming on GPUs with HASH Maohua Zhu, Ningyi Xu, Di Wu, Chunshui Zhao, Yangdong Deng, Yu Wang and Feng-Hsiung Hsu.
16:00-16:30	Coffee break
	Large Scale Techniques
16:30-17:00	Analysis of performance evaluation techniques for Large Scale Information Retrieval Ana Freire, Fidel Cacheda, Vreixo Formoso and Víctor Carneiro.
17:00-17:30	Evaluating inverted files for visual compact codes on a large scale Giuseppe Amato, Paolo Bolettieri, Fabrizio Falchi and Claudio Gennaro.
17:30-18:00	Open Discussion

Evaluating Inverted Files for Visual Compact Codes on a Large Scale

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ABSTRACT

The Bag-of-Words (BoW) or bag-of-features approach is the most widely adopted method for finding images that represent the same object or location given an image as a query and a large set of images as dataset. One of the reasons for the BoW success is that off-the-shelf text search engines can be used to build a distributed and robust system. Very recently, Vector of Locally Aggregated Descriptors (VLAD) have been shown to yield higher effectiveness than BoW. However, VLAD cannot be used in place of BoW on top of text search engines given that it is not a sparse vector of occurrence counts. In this paper, we propose combining a Surrogate Text Representation (SRT) approach with VLAD allowing indexing with traditional text search engines. While previous comparisons between VLAD and BoW were conducted using distinct indexing techniques, we show that the VLAD-SRT combination significantly outperforms BoW on the very same hardware and software infrastructure. The experiments show that VLAD-SRT outperforms BoW and that SRT does not significantly reduce the effectiveness of VLAD.

Keywords

bag of features, bag of words, local features, compact codes, image retrieval.

1. INTRODUCTION

In the last few years, local features [18] extracted from selected regions [23] have emerged as a promising method of representing image content in such a way that tasks of object recognition, and other similar (e.g. landmark recognition, copy detection, etc.) can be effectively executed. A

drawback of the use of local features is that a single image is represented by a large set (typically thousands) of descriptors that should be individually matched and processed in order to compare the visual content of two images. In principle, given an image as query and a dataset of visual contents in an image dataset, each dataset image should be compared with the query independently. In fact, each local feature of the query should be compared with all the local features of any dataset image. Moreover, candidate matches should be validated with geometric consistency checks typically using RANSAC [10]. Even if efficient data structure as kd-tree [11] are used to efficiently search candidate matching pairs in any two images, still the approach is not scalable.

For large scale content based image search, a very popular method is the Bag of Features or Bag of Words (BoW) [22] approach. This approach consists in replacing original key-point descriptions with the id of the most similar local feature in a predefined vocabulary. BoW descriptions of an image are a set of possible repeating words that can be indexed using traditional search engines. Searching a query image described with BoW consists in comparing sparse vector of occurrence counts of a vocabulary of local image features. However, as mentioned in [25], “a fundamental difference between an image query (e.g. 1500 visual terms) and a text query (e.g. 3 terms) is largely ignored in existing index design”.

Efficiency and memory constraints have been recently addressed by aggregating local descriptors into a compact vector representation. In particular, Fisher Vector (FV) [20] and VLAD [15] have shown better performance than BoW [17]. In this work we will focus on VLAD which is very similar to FV. In fact VLAD has been proved to be a simplified non-probabilistic version of FV that performs very similar to FV [17]. While BoW is a sparse vector of occurrence, VLAD is not. Thus, inverted files can not be directly applied for indexing and Euclidean Locality-Sensitive Hashing [8] is, as far as we know, the only technique tested with VLAD. Many other similarity search indexing techniques [24] could be applied to VLAD. A very promising direction is Permutation-Based Indexing [7, 6, 9]. In particular the MI-File allows using inverted files to perform similarity search with an ar-

bitrary similarity function. Moreover, in [12, 1] a Surrogate Text Representation (STR) derived from the MI-File has been proposed. The conversion of the image description in textual form allows employing the search engine off-the-shelf indexing and searching abilities with a little implementation effort.

In this paper we applied the STR technique to the VLAD descriptions comparing both effectiveness and efficiency with the state-of-the-art BoW approach on the very same hardware and software infrastructure using a publicly available and widely adopted 10M image dataset. Given that the VLAD-STR combination gives approximate results, we also compare its effectiveness with results obtained with a sequential scan. Moreover, we considered balancing efficiency and effectiveness with both BoW (using $tf*idf$) and VLAD-STR (varying the number of results used for re-ordering) approaches. Thus, we do not only compare VLAD-STR and BoW on specific settings but we show efficiency vs effectiveness graphs for both. Results confirm the higher performance obtained by VLAD with respect to BoW already showed in [15, 17] even when VLAD is combined with STR a off-the-shelf text search engine (i.e., Lucene) is used. Thus, our main contribution is the prove that VLAD, in combination with STR, can be used in place of BoW in Content Based Image Retrieval (CBIR) systems where text search engines are used for indexing preserving the improvement in effectiveness showed in [17]

The paper is organized as follows. Section 2 presents relevant previous works. In Section 3 we present the STR approach that is used for indexing VLAD with a text search engine. Results are presented in Section 4. Finally, in Section 5 we present our conclusions and describe future work.

2. RELATED WORK

2.1 Local features

Local features are visual descriptors [18] computed for local interest regions extracted from selected regions [23]. Good local features should be distinctive and at the same time robust to changes in viewing conditions as well as to errors of the detector. Developed mainly in Computer Vision, their typical applications include finding locations and particular objects, detecting image near duplicates and deformed copies. A drawback of the use of local features is that a single image is represented by a large set (typically thousands) of descriptors that should be individually matched and processed in order to compare the visual content of two images. Even if the use of local features their original form for CBIR has been studied in [2, 3], for very large scale image retrieval transformation of the local features is needed. The most famous approach is BoW.

2.2 Bag of Words (BoW)

The BoW approach was initially proposed in [22] and has been studied in many papers. The goal of the BoW approach is to substitute each description of the region around an interest points (i.e., each local feature) of the images with visual words obtained from a predefined vocabulary in order to apply traditional text retrieval techniques to CBIR.

The first step is selecting some visual words creating a vo-

cabulary. The visual vocabulary is typically built clustering local descriptors of the dataset k -means. The second step assigns each local feature of the image to the identifier of the first nearest word in the vocabulary. For speedup this second phase approximate kd-tree are often used at a small effectiveness price. At the end of the process, each image is described as a set of visual words. The retrieval phase is then performed using text retrieval techniques considering a query image as disjunctive text-query. Typically, the *cosine* similarity measure in conjunction with a term weighting scheme is adopted for evaluating the similarity between any two images.

However, in many cases efficiency is not yet satisfactory. In fact, a query image is associated with thousands of visual words. Therefore, the search algorithm on inverted file has to access thousands of different posting lists. From the very beginning [22] some words reduction techniques were used (e.g. removing 10% of the more frequent images). In [4], $tf*idf$ [21] revealed very good performance in improving efficiency of the BoW approach with a reduced lost in effectiveness. In this work, we make use of the parametric $tf*idf$ approach to allow trade-offs between efficiency and effectiveness in the BoW approach.

2.3 Fisher Vector

Fisher kernels [13] describe how the set of descriptors deviates from an average distribution, modeled by a parametric generative model. Fisher kernels have been applied in the context of image classification [19] and large scale image search [20]. In [17] it has been proved that Fisher vectors (FVs) extend the BoW. While the BoW approach counts the number of descriptors assigned to each region in the space, FV also encodes the proximate location of the descriptors in each region and has a normalization that can be interpreted as an IDF term. The FV image representation proposed by [19] assumes that the samples are distributed according to a Gaussian Mixture Model (GMM) estimated on a training set. Results reported in [17] reveal that FV indexed using LSH outperforms BoW.

2.4 VLAD

The VLAD representation was proposed in [15]. As for the BoW, a codebook $\{\mu_1, \dots, \mu_K\}$ is first learned using a cluster algorithm (e.g. k -means). Each local descriptor x_t is then associated to its nearest visual word $NN(x_t)$ in the codebook. For each codeword the differences between the vectors x_t assigned to μ_i are accumulated:

$$v_i = \sum_{x_t: NN(x_t)=i} x_t - \mu_i$$

The VLAD is the concatenation of the accumulated vectors, i.e. $V = [v_1^T \dots v_K^T]$.

Two normalization are performed: first, a power normalization with power 0.5; second, a L2 normalization. After this process two descriptions can be compared using the inner product.

The observation that descriptors are relatively sparse and very structured suggests a principal component analysis (PCA) that is usually performed to reduce the size of the Kd -dimensional VLAD vectors. In this work, we decide not

to use dimensionality reduction techniques because we will show that our space transformation approach is independent from the original dimensionality of the description. In fact, the STR approach that we propose, transforms the VLAD description in a set of words from a vocabulary that is independent from the original VLAD dimensionality. In our proposal, PCA could be used to increase efficiency of the STR transformation.

In [17], it has been shown that VLAD is a simplified non-probabilistic version of FV: VLAD is to FV what k-means is to GMM clustering. The k-means clustering can be viewed as a non-probabilistic limit case of GMM clustering.

In [17] Euclidean Locality-Sensitive Hashing and its variant have been proposed to efficiently search VLAD descriptions. In fact, text search engine cannot be used with the VLAD description as it is. In this paper, we will present a space transformation technique that allows the use of text search engine for VLAD.

3. PERSPECTIVE TRANSFORMATION AND SURROGATE TEXT REPRESENTATION

In this paper we propose to index VLAD using a text encoding that allows using any text retrieval engine to perform image similarity search. As discussed later, we implemented these ideas on top of the Lucene text retrieval engine.

In a nutshell, we provide a straightforward and effective tool for transforming global descriptors (GDs), for which is defined a similarity function, in textual form by allowing developers to employ an off-the-shelf conventional text-based search engine to set up a content-based information retrieval system with a little implementation effort. The content-based system developed offers the users the possibility of full-text search combined with content-based searches.

The approach to *encode Global Features* leverages on the perspective based space transformation developed in [6, 12]. The idea at the basis of this technique is that when two global descriptors (GDs) are very similar, with respect to a given similarity function, they 'see' the 'world around' them in the same way. In the following, we will see that the 'world around' can be encoded as a *surrogate text representation* (STR), which can be managed with an inverted index by means of a standard text-based search. The conversion of the GDs in textual form allows us to employ the search engine off-the-shelf indexing and searching abilities with a little implementation effort.

3.1 SRT Generation

Let \mathcal{D} be a domain of GDs, and $d : \mathcal{D} \times \mathcal{D} \rightarrow \mathbb{R}$ a distance function able to assess the dissimilarity between two GDs of \mathcal{D} . Let $R \in \mathcal{D}^m$, be a vector of m *distinct* GDs (*reference descriptors* or *pivots*), i.e., $R = (r_1, \dots, r_m)$. We denote the vector of positions of R , ranked by increasing distance with respect to any GD $o \in \mathcal{D}$ by $\bar{p}(o) = (p_1(o), \dots, p_m(o))$. For instance, if $p_3(o) = 2$ then r_3 is the 2nd nearest object to o among those in R .

The objective is to define a function that transforms a global

descriptor into a sequence of terms (ie, a textual document) that can be fed into a text search engine as for instance Lucene. Of course, the ultimate goal is to obtain that the distance between the documents and the query is an approximation of the original distance function of the global descriptors. To achieve this, we associate each element $r_i \in R$ with a unique alphanumeric keyword τ_i , and define a function $t^k(o)$ that returns a space-separated concatenation of zero or more repetitions of τ_i keywords, as follows:

$$t^k(o) = \bigcup_{j=1}^k \bigcup_{i=1}^{k+1-p_j^k(o)} \tau_i$$

where, by abuse of notation, we denote the space-separated concatenation of keywords with the union operator \cup . The function $t^k(o)$ is used to generate the STR to be used for both indexing and querying purposes. k assumes in general the values k_x for indexing and k_q for querying. For instance, consider the case exemplified in Figure 1, and let us assume $\tau_1 = A, \tau_2 = B$, etc. The function t^k will generate the following outputs

$$\begin{aligned} t^{k_x}(o_1) &= \text{"E E E B B A"} \\ t^{k_x}(o_2) &= \text{"D D D C C E"} \\ t^{k_q}(q) &= \text{"E E A"} \end{aligned}$$

As can be seen intuitively, strings corresponding to o_1 and q are more similar to those corresponding to o_2 e q , this approximate the original distance d . Without going to the mathematical details, we leverage on the fact that a text based search engine will generate a vector representation of STRs generated with $t^{k_x}(o)$ and $t^{k_q}(q)$ containing the number of occurrences of words in texts. This is the case of the simple term-frequency weighting scheme. This means that, if for instance keyword τ_i corresponding to the reference object r_i ($1 \leq i \leq m$) appears n times, the i -th element of the vector will contain the number n , and whenever τ_i does not appear it will contain 0. With simple mathematical manipulations, it is easy to see how applying the cosine similarity on the query vector and a vector in the database corresponding to $t^{k_x}(o)$ and $t^{k_q}(q)$ respectively, we get a degree of similarity that reflects the similarity order of reference descriptors (pivots) around descriptors in the original space. For more information on how the technique works from the mathematical point of view, we remind the reader to [12, 1]. Moreover, in the recent work [5] we studied the impact k_x on the effectiveness of the search.

3.2 Reordering Search Results

The idea described so far uses a textual representation of the Global Descriptors and a matching measure based on a similarity offered by standard search engines to order the descriptors in the dataset in decreasing similarity with respect to the query. The result set is more precise if we order it using the original distance function d .

Suppose we are searching for the k most similar (nearest neighbors) descriptors to the query. We can improve the quality of the approximation by re-ranking, using the original distance function d , the first c ($c \geq k$) descriptors from the approximate result set at the cost of more c distance computations. We will show that this technique significantly improves the accuracy, though only requiring a very

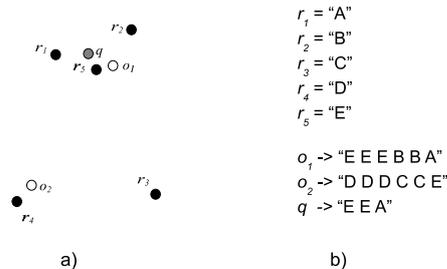


Figure 1: Example of perspective based space transformation and Surrogate Text Representation. a) Black points are reference objects; white points are data objects; the gray point is a query. b) Encoding of the data objects in the STR.

low search cost. In fact, when c is much smaller than the size of the dataset, this extra cost can be considered negligible with respect to the cost of accessing the inverted file. For instance, when k is 10 and $c = 1,000$, with a dataset size of 1,000,000 it means that we have to reorder a number of descriptors equivalent to just 0.1% of the entire dataset. Usually, this is not true for other access methods, for instance tree-based access methods, where the efficiency of the search algorithms strongly depends on the amount of descriptors retrieved.

4. EXPERIMENTS

4.1 Setup

INRIA Holidays [16, 17] is a collection of 1,491 holiday images. The authors selected 500 queries and for each of them a list of positive results. As in [14, 15, 17], to evaluate the approaches on a large scale, we merged the Holidays dataset with the Flickr1M¹ collection. SIFT features have been extracted and words selected by Jegou et al. for both the Holidays and the Flickr 1M datasets². For the BoW approach we used the 20K vocabulary.

In the following, as in [15, 17], we combine the INRIA Holidays and Flickr1M datasets in order to perform experiments on a large scale. The ground-truth is the one built on the INRIA Holidays dataset alone, but it is largely accepted that no relevant images can be found between the Flickr1M images.

For representing the images using the VLAD approach, we selected 64 reference features using k -means over a subset of the Flickr1M dataset. As explained Section 3, a drawback of the perspective based space transformation used for indexing the VLAD with a text search engine is that it is an approximate technique. However, to alleviate this problem, it is possible to reorder the best results using the actual distance between the VLAD descriptions. For the space transformation we used 4,000 pivots randomly selected from the Flickr1M dataset.

During the experimentation also 256 reference features were

¹<http://press.liacs.nl/mirflickr/>

²<http://lear.inrialpes.fr/~jegou/data.php>

used for the VLAD description and up to 10,000 pivots were selected for the space transformation but the results were only slightly better than the ones presented while efficiency significantly reduced.

All experiments were conducted on a Intel Core i7 CPU, 2.67 GHz with 12.0 GB of RAM a 2TB 7200 RPM HD for the Lucene index and a 250 GB SSD for the VLAD reordering. We used Lucene v3.6 running on Java 6 64 bit over Windows 7 Professional.

The quality of the retrieved images is typically evaluated by means of precision and recall measures. As in many other papers [14, 20, 17], we combined this information by means of the mean Average Precision (mAP), which represents the area below the precision and recall curve.

4.2 Results

In Table 1, we report the mAP obtained with the BoW approach varying the size of the query in terms of average number of distinct words. The query words have been filtered using the $tf*idf$ approach as mentioned in Section 2.2. The average number of words per image, as extracted by the INRIA group, is 1,471 and they were all inserted in the index without any filtering. The filtering was used only for the queries and results are reported for average number of distinct words up to 250. In fact, bigger queries result in heavy load of the system. It is worth to mention that we were able to obtain 0.23 mAP performing a sequential scan of the dataset with the unfiltered queries.

The results show that while the BoW approach is in principle very effective (i.e. performing a sequential scan), the high number of query visual words needed for achieve good results significantly reduce his usability. As mentioned in [25], “a fundamental difference between an image query (e.g. 1,500 visual terms) and a text query (e.g. 3 terms) is largely ignored in existing index design. This difference makes the inverted list inappropriate to index images”.

BoW		
avg#Words	mAP	avg mSec
7	0.03	525
16	0.07	555
37	0.11	932
90	0.14	1463
233	0.15	2343

Table 1: Effectiveness (mAP) and efficiency (mSec) with respect to the average number of distinct words per query obtained with the BoW approach varying the query size.

In Table 2, we report the results obtained using the VLAD approach in combination with the use of the STR illustrated in Section 3. As explained in 4.1, given that for indexing the images we used a STR, it is useful to reorder the better results obtained from the text search engine using the actual VLAD distance. Thus, we report mAP and avg mSec per query for the non-reordering case and for various values of

results used for reordering. The reordering phase dominates the average query time but it significantly improves effectiveness especially if only 100 or 1,000 objects are considered for reordering. As mentioned before, we make use of SSD for speed-up reordering phase but even higher efficiency could be obtained using PCA as proposed in [17]. Please note that even if the reordering phase cost for VLAD can be reduced the reported results already show that VLAD outperform BoW.

It is worth to mention that we also performed a sequential scan of the entire dataset obtaining a mAP of 0.34 for VLAD. In fact, as depicted in 3, the results obtained with the VLAD-STR approach are an approximation of the results obtained with a complete pair wise comparison between the query and the dataset object. The same is true when LSH indexing is used as in [17]. Results show that the approximation introduced by STR does not impact significantly the effectiveness of the system when at least 1,000 objects are considered for reordering.

VLAD		
#reordered	mAP	avg mSec
0	0.13	139
100	0.24	205
1000	0.29	800
2000	0.30	1461
4000	0.31	2784

Table 2: Effectiveness (mAP) and efficiency (mSec) obtained with the VLAD approach in combination with STR, with respect to the number of results used for reordering.

In Figure 2 we plot mAP with respect to the average query execution time for both BoW and VLAD as reported in Table 1 and Table 2. The graph underlines both the efficiency and effectiveness advantages of the VLAD with respect to the BoW approach.

5. CONCLUSIONS AND FUTURE WORK

In this work, we proposed the usage of SRT in combination with VLAD descriptions in order to index VLAD with off-the-shelf text search engines. Using the very same hardware and text search engine (i.e., Lucene), we were able to compare with the state-of-the-art BoW. Results obtained for BoW confirm that the high number of visual terms in the query significantly reduces efficiency of inverted lists. Even if results showed that this can be mitigated reducing the number of visual terms in the query with a $tf*idf$ weighting scheme, the VLAD-SRT significantly outperforms BoW in terms of both efficiency and effectiveness. The efficiency vs effectiveness graph reveals that VLAD-SRT is able to obtain the same values of mAP obtained with BoW for an order of magnitude less in response time. Moreover, for the same response time, VLAD-SRT is able to obtain twice the mAP of BoW.

Future work includes VLAD-SRT improving the reordering

phase. With regards to efficiency, PCA could be used on VLAD as suggested in [17]. Moreover, in recognition scenarios (e.g., landmark recognition) the reordering phase typically involves geometric consistency checks performed using RANSAC. This could be also done with the VLAD description.

As mentioned in the paper VLAD is essentially a non probabilistic version of the Fisher Kernels that typically results in almost the same performance. It would be interesting to test the STR approach also with Fisher Kernels comparing with both VLAD-STR and BoW.

6. REFERENCES

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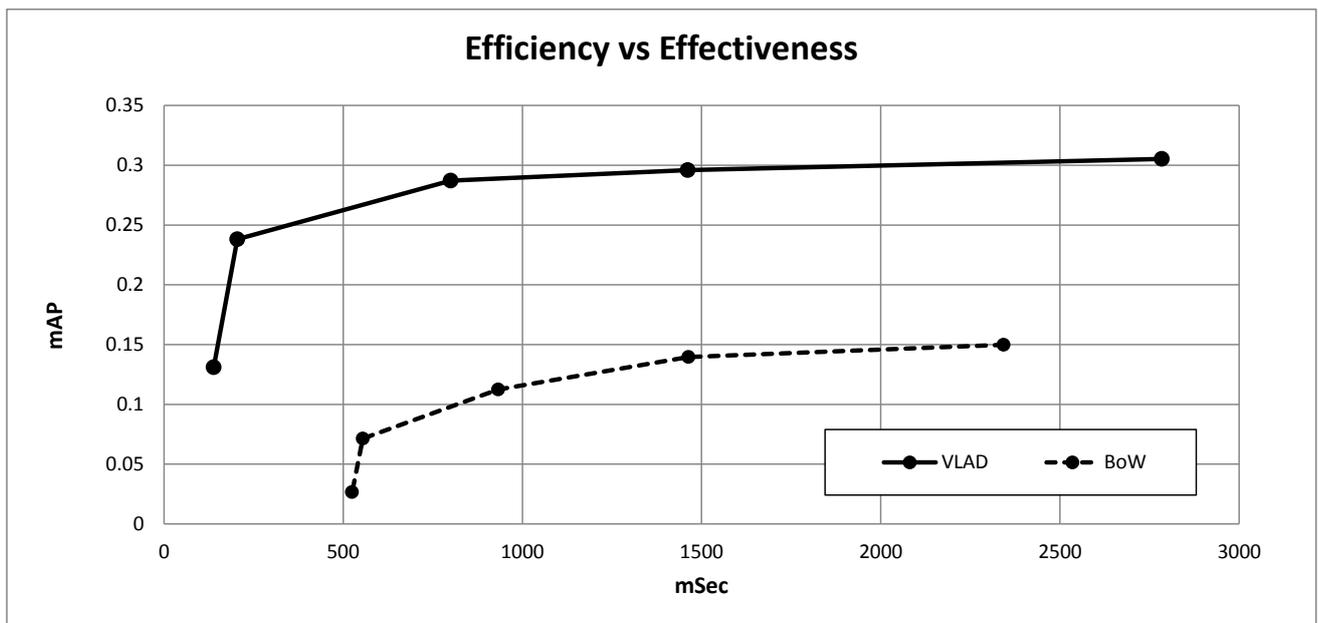


Figure 2: Effectiveness (mAP) with respect to efficiency (mSec per query) obtained by VLAD and BoW for various settings.

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