Product Lines for Service Oriented Applications - PL for SOA

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PL for SOA proposes, formally, a software engineering methodology, development techniques and support tools for the provision of service product lines. We propose rigorous modeling techniques for the specification and verification of formal notations and languages for service computing with inclinations of variability. Through these cutting-edge technologies, increased levels of flexibility and adaptivity can be achieved. This will involve developing semantics of variability over behavioural models of services. Such tools will assist organizations to plan, optimize and control the quality of software service provision, both at design and at run time by making it possible to develop flexible and cost-effective software systems that support high levels of reuse. We tackle this challenge from two levels. We use feature modeling from product line engineering and, from a services point of view, the orchestration language Orc. We introduce the Smart Grid as the service product line to apply the techniques to.

1 Introduction

Business environments command innovation, increasingly shorter time-to-market and efficiency. Product line technology, is increasingly finding its way to the software sector, allowing companies to sustain growth and achieve market success [13].

Service-Oriented Architecture (SOA) has emerged as a standard-based computing model for designing, building and deploying flexible distributed software applications. SOA emphasizes extremely loosely-coupled design approaches where disparate systems with different computing platforms can collaborate and evolve without major changes to their core architectures. Services are designed as self-contained modules that can be advertised, discovered, composed and negotiated on demand.

Software Product Lines (SPL) are families of software systems that share common functionality, but each member also has variable functionality. The main goal of SPL is the agile and speedy development of member systems by taking advantage of reusable assets from all phases of the development life cycle. This goal is similar to SOA’s goals [1].

Despite the wide academic and industrial activities related to SOA, no systematic end-to-end methodology exists to analyze and design service-oriented applications. On the other hand, SPL is an established field with considerable methodological support. It is then clear that combining SOA and SPL is a powerful way to build complex evolving systems.

The combination of SPL and SOA development practices is a new development paradigm that can help provide the answers to the need for agility, versatility and economy. SOA and SPL approaches to software development share a common goal. They both encourage an organization to reuse existing assets and capabilities rather than repeatedly redeveloping them for new systems. These approaches enable organizations to capitalize on reuse to achieve desired benefits such as productivity gains, decreased development costs, improved time to market, higher reliability and competitive advantage. Their distinct goals may be stated as follows [14, 26, 27]:

L. Kovacs, R. Pugliese, and F. Tiezzi (Eds.): Workshop on Automated Specification and Verification of Web Systems (WWV 2011)  
EPTCS 61, 2011, pp. 34–48 doi:10.4204/EPTCS.61.3  
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SOA To enable the assembly, orchestration and maintenance of enterprise solutions to quickly react to changing business requirements.

SPL To systematically capture and exploit commonality among a set of related systems while managing variations for specific customers or market segments.

The goal of our research is to formally answer the question, ‘How can the use of product line practices support service-oriented applications?’ SOA and SPL have their differences and similarities and we are exploiting the similarities in order to naturally formalize SPL [20] and service-oriented applications [34].

This work is part of a longer-term research effort to develop a PL for SOA formalisms. The paper introduces a first step towards this goal. We have found an existing formalism for modeling variability in product lines that can be combined with a SOA calculus and thus create a PL for SOA formalism.

Modeling variability in product families has been the subject of extensive study in the literature on SPL, especially that concerning feature modeling [12, 15, 23]. Variability modeling addresses how to define which features or components of a system are optional, alternative, mandatory, required or excluded; formal methods are then developed to show that a product belongs to a family, or to derive instead a product from a family, by means of a proper selection of the features or components. Variability management is the key aspect that differentiates SPL engineering from ‘conventional’ software engineering.

Labelled Transition Systems (LTSs) have been used successfully to reason about system behaviour. Modal Transition Systems (MTSs) are an extension of LTSs that distinguish between mandatory, possible and unknown behaviour. MTSs have been studied for some time as a means for formally describing partial knowledge of the intended behaviour of software systems [3].

MTSs have been proposed as a formal model for product families [19, 28], allowing one to embed in a single model the behaviour of a family of products that share the basic structure of states and transitions, transitions which can moreover be seen as mandatory or possible for the products of the family. In [16], the MTS concept was pushed to a more general form, allowing more precise modeling of the different kinds of variability that can typically be found in the definition of a product family.

In [8], a temporal logic for modeling variability in product families was proposed by taking advantage of the way in which deontic logic formalises concepts like violation, obligation, permission and prohibition, using MTSs as the underlying semantic model. In [9, 11], a model checker is presented based on a formal framework consisting of  \( \forall \alpha \text{CTL} \) (a variability and action-based branching-time temporal logic) with its natural interpretation structure (MTSs). Product derivation is defined inside the framework and logical formulae are used as variability constraints as well as behavioural properties to be verified for families and products alike. A first attempt to apply this tool to the analysis of variability in behavioural descriptions of families of services is presented in [10].

From a service orientation point of view, we believe that Cook and Misra’s Orc [33] will highlight the SPL aspects necessary to meet our goals. An operational semantics of Orc based on LTSs appears in [35]. Thus, it appears from a first glance that we can extend the LTS semantics of Orc to a semantics over MTSs and merge the different scopes of SOA and SPL creating a PL for SOA formalism. The formal definition of such a semantics is left for future work.

The paper is structured as follows. In Section 2 we review some related work and some product line basics from a feature modeling perspective and present the orchestration language Orc and its usefulness. Section 3 combines ideas from product line engineering and the service-oriented concurrency calculus of Orc. Section 4 highlights the case study over which the tools are applied. We conclude in Section 5 with some remarks on future work.
2 Related Work and Preliminaries

Various authors have contributed to the study of combining SOA and SPL practices and most are still in the preliminary stages of defining what SPL for SOA means: [1] presents a method to design service-oriented applications based on SPL principles by applying variability analysis techniques to Web Services to design customized service-based applications.

In [4][36], the authors study the common problems relating to SOA and SPL approaches and propose ways of reconciling the two, while [5] demonstrates how model-driven engineering can help with injecting a set of required commonalities and variability of a software product from a high-level business process design to the lower levels of service use. To realize the method and activities involved, a supply chain management application is used.

Günther et al. [21] propose a differentiated development process for SPLs implementing a SOA. They use an extensive example of a web store to show how parts of this process can be solved technically with already developed methods for feature modeling and management using Web Services.

An approach to service identification methods is proposed in [22] to bridge the feature models of product lines and the business process models in service orientation and enables functions to be expressed as services.

2.1 Product Line Modeling

As a first step we have used feature diagrams to model product lines. Feature diagrams are a family of popular modeling languages used for engineering requirements in SPL represented as the nodes of a tree, with the product family being the root and having the following features [23]:

- **optional** features, may be present in a product only if their parent is present;
- **mandatory** features, are present in a product if and only if their parent is present;
- **alternative** features, are a set of features among which one and only one is present in a product if their parent is present.

When additional constraints are added to a feature diagram, this results in a feature model. Constraints come in several flavours and we consider the following constraints:

- **requires** is a unidirectional relation between two features indicating that the presence of one feature requires the presence of the other;
- **excludes** is a bidirectional relation between two features indicating that the presence of either feature is incompatible with the presence of the other.

2.2 Service-Oriented Modeling

Orc has proved to be a high-level language that makes the notoriously difficult task of building distributed systems easier. It coordinates interactions among basic subsystems, called sites, by use of a small number of combinators. It allows integration of components and assumes that structured concurrent programs should be developed much like structured sequential programs, by decomposing a problem and combining the solutions with the combinators.

Orc permits structuring programs in a hierarchical manner, while permitting interactions among subsystems in a controlled way [24]. The basis for its design is to allow integration of components and is founded on the premise of combination. Thus, combinators are a very important part of the theory.
An Orc program consists of a goal expression (either primitive or a combination of two expressions) and a set of definitions. The goal expression is evaluated in order to run the program. The definitions are used in the goal and in other definitions. A component is generally called a service; Orc adopts the more neutral term *site* which is the most primitive Orc expression. It represents an external program and is said to publish a value when a value is returned in response to a call.

Given the formalism we are working on, we will not dwell on the Orc programming language but concentrate on the Orc calculus.

### 2.3 The Orc Calculus

We present the calculus informally in this paper. The Orc calculus is based on the execution of expressions. Expressions are built up recursively using Orc’s concurrent combinators [25]. When executed, an Orc expression calls services and may publish values. Different executions of the same expression may have completely different behaviour; they may call different services, receive different responses from the same service and publish different values. Orc expressions use sites to refer to external services. A site may be implemented on the client’s machine or on a remote machine. A site may provide any service; it could run sequential code, transform data, communicate with a Web Service or be a proxy for interaction with a human user.

A site call is defined as \( A(x) \), where \( A \) is a site name and \( x \) is a list of actual inputs. The following table lists the fundamental sites of Orc.

<table>
<thead>
<tr>
<th>Site</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>if( b ):</td>
<td>Returns a value if ( b ) is true, and otherwise does not respond.</td>
</tr>
<tr>
<td>Rtimer( t ):</td>
<td>Returns a value after exactly ( t ), ( t \geq 0 ), time units.</td>
</tr>
<tr>
<td>Signal():</td>
<td>Returns a value immediately. Same as if( \text{true} ).</td>
</tr>
<tr>
<td>0:</td>
<td>Blocks forever. Same as if( \text{false} ).</td>
</tr>
</tbody>
</table>

Though the Orc calculus itself contains no sites, for our purposes we consider another fundamental site which is essential to writing useful computations. The site *let* is the identity site; when passed one argument, it publishes that argument, and when passed multiple arguments it publishes them as a tuple.

Orc has four combinators to compose expressions: the parallel combinator \( | \), the sequential combinator \( \succ x \succ \), the asymmetric parallel combinator \( < x < \), and the otherwise combinator \( ; \). When composing expressions, the \( \succ x \succ \) combinator has the highest precedence, followed by \( | \), then \( < x < \) and finally \( ; \) has the lowest precedence [25].

1. The independent parallel combinator, \(( A \mid B )\), allows independent concurrent execution of \( A \) and \( B \). The sites called by \( A \) and \( B \) individually are called by \(( A \mid B )\) and the values published by \( A \) and \( B \) are published by \(( A \mid B )\).

2. The sequential combinator, \(( A \succ x \succ B )\), initiates a new instance of \( B \) for every value published by \( A \) whose value is bound to name \( x \) in that instance of \( B \). The values published by \(( A \succ x \succ B )\) are all instances of those published by \( B \). If \( x \) is not used in \( B \), this combinator is abbreviated by \(( A \gg B )\).

3. The asymmetric parallel combinator, \(( A < x < B )\), evaluates \( A \) and \( B \) independently, but the site calls in \( A \) that depend on \( x \) are suspended until \( x \) is bound to a value; the first value from \( B \) is bound to \( x \), evaluation of \( B \) is then terminated and suspended calls in \( A \) are resumed; the values published by \( A \) are those published by \(( A < x < B )\). If \( x \) is not used in \( B \), this combinator is abbreviated by \(( A \ll B )\).
4. The otherwise combinator, \((A; B)\), executes A and if it completes and has not published any values, then executes B. If A did publish one or more values, then B is ignored. The publications of \((A; B)\) are thus those of A if A publishes, or those of B otherwise [24].

2.4 Modal Transition Systems

MTSs are now an accepted formal model for defining behavioural aspects of product families [3, 8, 11, 16, 19, 28]. An MTS is an LTS with a distinction between may and must transitions, seen as optional or mandatory features for a family’s products. For a given product family, an MTS can model

- its underlying behaviour, shared among all products, and
- its variation points, differentiating between products.

An MTS cannot model advanced variability constraints regarding alternative features nor those regarding the requires and excludes inter-feature relations [8]. Such advanced variability constraints can be formalized by means of an associated set of logical formulae expressed in the variability and action-based branching-time temporal logic vaCTL (interpreted over MTSs) [9].

We now formally define MTSs and — to begin with — their underlying LTSs.

**Definition 2.1.** An LTS is a quadruple \((Q, A, q_i, \delta)\), with set \(Q\) of states, set \(A\) of actions, initial state \(q_i \in Q\), and transition relation \(\delta \subseteq Q \times A \times Q\).

One may also write \(q \xrightarrow{a} q'\) for \((q, a, q') \in \delta\).

In an LTS, transitions are defined to be possible (may) or mandatory (must).

**Definition 2.2.** An MTS is a quintuple \((Q, A, q_i, \delta^\odot, \delta^\circ\)) such that the quadruple \((Q, A, q_i, \delta^\odot \cup \delta^\circ)\) is an LTS, called its underlying LTS. An MTS has two transition relations: \(\delta^\circ \subseteq Q \times A \times Q\) is the may transition relation, expressing possible transitions, while \(\delta^\odot \subseteq Q \times A \times Q\) is the must transition relation, expressing mandatory transitions. By definition, \(\delta^\odot \subseteq \delta^\circ\).

One may also write \(q \xrightarrow{a} \circ q'\) for \((q, a, q') \in \delta^\odot\) and \(q \xrightarrow{a} \odot q'\) for \((q, a, q') \in \delta^\odot\).

The inclusion \(\delta^\odot \subseteq \delta^\circ\) formalises that mandatory transitions must also be possible. Reasoning on the existence of transitions is thus like reasoning with a 3-valued logic with the truth values true, false, and unknown: mandatory transitions (\(\delta^\odot\)) are true, possible but not mandatory transitions (\(\delta^\odot \setminus \delta^\odot\)) are unknown, and impossible transitions ((\(q, a, q') \notin \delta^\odot \cup \delta^\odot\)) are false.

To model feature model representations of product families as MTSs one thus needs a ‘translation’ from features to actions (not necessarily a one-to-one mapping) and the introduction of a behavioural relation (temporal ordering) among them. A family’s products are then considered to differ w.r.t. the actions they are able to perform in any given state of the MTS. This means that the MTS of a product family has to accommodate all the possibilities desired for each derivable product, predicating on the choices that make a product belong to that family.

Figure 3 below is an example of an MTS: dashed arcs are used for the may transitions that are not must transitions (\(\delta^\odot \setminus \delta^\odot\)) and solid ones for must transitions (\(\delta^\odot\)).

Given an MTS description of a product family, an LTS describing a product is obtained by preserving at least all must transitions and turning some of the may transitions (that are not must transitions) into must transitions as well as removing all of the remaining may transitions.

**Definition 2.3.** Let \(\mathcal{F} = (Q, A, q_i, \delta^\odot, \delta^\circ)\) be an MTS specifying a product family. A set of products specified as a set of LTSs \(\{\mathcal{P}_i = (Q_i, A, q_i, \delta_i) \mid i > 0\}\) is derived by considering each transition relation \(\delta_i\) to be \(\delta^\odot \cup R\), with \(R \subseteq \delta^\circ\), defined over a set of states \(Q_i \subseteq Q\), so that \(q_i \in Q_i\), and every \(q \in Q_i\) is reachable from \(q_i\) via transitions from \(\delta_i\).
More precisely, we say that \( P_i \) is a product of \( F \), denoted by \( P_i \vdash F \), if and only if \( q_i \vdash q \) holds, for some \( q_i \in Q_i \) and \( q \in Q \), if and only if:

- whenever \( q \xrightarrow{a} q' \), for some \( q' \in Q \), then \( \exists q'_i \in Q_i \) : \( q_i \xrightarrow{a} q'_i \) and \( q'_i \vdash q' \), and
- whenever \( q_i \xrightarrow{a} q'_i \), for some \( q'_i \in Q_i \), then \( \exists q' \in Q \) : \( q \xrightarrow{a} q' \) and \( q'_i \vdash q' \).

The products derived in this way obviously might not satisfy the aforementioned advanced variability constraints that MTSs cannot model. However, as said before, \( \forall \text{CTL} \) can be used to express those constraints and \([10]\) contains an algorithm to derive from an MTS all products that are valid w.r.t. constraints expressed in \( \forall \text{CTL} \).

3 Service-Oriented Product Line

In order to model a service product line, we merge the feature modeling and Orc approaches. We show here that the Orc calculus can be viewed from product line-feature modeling perspective and, hence, the resulting calculus can sufficiently specify service-oriented product lines. We believe that the Orc combinator can be given a semantics over MTSs that would result in an almost one-to-one correspondence with the features and inter-feature relations of product families:

- The independent parallel combinator, \((A \mid B)\), can be used to specify mandatory features. This is because there is no direct communication or interaction between these two computations and they are instantiated independently and in parallel.

- The sequential combinator, \((A <x> B)\), can be used to specify required features. This follows from the fact that \( B \) is never instantiated unless \( A \) publishes a value which is bound to \( x \) and utilized as input in \( B \). Thus, \( B \) requires published values from \( A \).

- The asymmetric parallel combinator, \((A \ll x\ll B)\), can specify optional features. Since both \( A \) and \( B \) are instantiated in parallel and those computations of \( A \) that require a value from \( B \) are suspended, this combinator may ignore the published value from \( B \) in order to incorporate optionality.

- The otherwise combinator, \((A; B)\), can be used to specify excluding features especially when there is a preferred outcome or priority. It follows because the computation of either \( A \) or \( B \) means that the other cannot be instantiated or has already failed.

We do not see how to directly cater for the alternative features from the combinator. However, we foresee the use of Orc’s powerful composition of the combinator to reason about them. We then intend to look at an alternative feature as a choice between two computations from which we let only one proceed. This is the essence of mutual exclusion. We consider a product in which we choose feature \( M \) if \( A \) happens, while otherwise we choose \( N \) (i.e. if \( B \) happens). We represent \( A \) and \( B \) as sites and \( M \) and \( N \) as expressions and use site \( flag \) to record which of \( A \) and \( B \) responds first.

\[
\text{if}(\text{flag}) \Rightarrow M \mid \text{if}(\neg \text{flag}) \Rightarrow N \leftarrow \text{flag} \in (A \Rightarrow \text{let(true)}) \mid (B \Rightarrow \text{let(false)})
\]

In the future, we plan to extend the LTS semantics of Orc to a semantics over MTSs to merge the different scopes of SOA and SPL and create a PL for SOA formalism.
4 Case Study

The energy utilities industry may be one of the last great technological frontiers, due to the fact that it has experienced little innovation over its lifespan and it is quickly approaching the end of its design life. However, the utility industry is about to embark on a revolutionary journey: the Smart Grid. Utilities and information technology companies will be surrounding the electric grid with a digital grid that will provide consumers and businesses with many value propositions [17].

One of the key components to this ‘smart’ electric grid is the upgrade to a two-way communications technology. This technology, partially fueled by governments supporting the modernization of the electric grid, requires one of the largest IT ‘upgrades’ that we will see in decades, and provides new product, service and market opportunities for utilities, generators, power traders and information technology companies [2].

We have a long way to go to turn this antiquated grid into a Smart Grid. However, using SOAs which lead to decreasing the time to market we may be able to have a fast response to the market needs. The applications will entail a fast time-to-market response, correctness, reusability, maintainability, testability and evolvability — besides low cost.

Furthermore, like the Internet it will require a standard layered and distributed architecture in order to deliver electricity over a two-way protocol from supplier to consumer utilizing independent components that must cooperate. SPLs and SOAs can provide several of these requirements due to the inherent flexibility in composing more sophisticated complex systems.

Suppose that your utility company has developed an intelligent electrical power system that leverages increased use of communications and information technology in the generation, delivery and consumption of electrical energy. Your company provides a choice among a family of products with different price tags and different functionalities. The basic architecture provides three products:

1. **Integration of renewables**, offering storage capacity, vehicle to grid and electric vehicles.
2. **Demand response**, offering efficient markets, load shifting and incorporating all end users.
3. **Grid monitoring management**, offering smart meters, self-healing capability and integrated communications.

The coordination component uses predefined external services (one for each business sector) to retrieve a list of alternatives, say for storage, load shifting or billing through the smart meters.

The basic product can be enhanced in two ways:

1. Adding the possibility to choose what company to source your electricity and in case you have generation capacity, choosing whom you will sell your excess power to, from a set of utilities in order to retrieve the best quotes through more than one service.
2. Adding the possibility for the user to make a reservation for the supply of extra electricity. This is accomplished by means of an added component that requests an external forecasting service to predict what sources of electricity generation are available and how much demand exists.

These enhancements can be combined to obtain four different products of the family. A greater level of flexibility in the service may be added by incorporating dynamic roles.

As the grid becomes more intelligent and more complex, the tools to operate it become increasingly important. Hence the need for interoperability (SOA), flexibility and variability (SPL). Our interest in undertaking this case study lies in specifying electricity provision as a service and the Smart Grid as a service product line.
4.1 The Smart Grid as a Product Line

The generic Smart Grid will be modeled as a family of products with basic components for basic products and specialized properties for some of the products, such as:

- storage;
- renewables, varying with weather, time, season and other intermittent effects;
- load shifting, the practice of managing electricity supply and demand so that peak energy use is shifted to off-peak periods;
- vehicle to grid (V2G), establishing a viable transparent business model, guaranteeing the availability and controllability of electric vehicles (EV) and V2G capacity as well as accurate forecasting of renewable energy supply and demand.

Load shifting and V2G can reduce the energy storage capacity required to maintain power quality.

From the Smart Grid family in Figure 1, we can develop up to four different products, all the while utilizing the basic architecture. Similarly, given an MTS model of the Smart Grid family, we can use Definition 2.3 to derive products.

![Figure 1: Feature model for the Smart Grid family](image)

One of the most obvious ones is a product without the integration of renewables, shown in Figure 2, which represents most of the existing electricity grids today and in which all the features are mandatory.

This product contains a Demand Response component, referring to dynamic demand mechanisms to manage customer consumption of electricity in response to supply and the programs to achieve that goal.

From the utility company point of view, there is a virtual power plant where the supply of electricity is managed. In place are technologies that allow the utility to talk to devices inside the customer premise. They include such things as load control devices, smart thermostats and home energy consoles for sensing, so as to provide information to consumers and operators so that they better understand consumption patterns and make informed decisions for more effective use of energy [30].

These are essential to allow customers to reduce or shift their power use during peak demand periods. Demand response solutions play a key role in several areas: pricing, emergency response, grid reliability, infrastructure planning and design, operations and deferral.
The part of the MTS model of the Smart Grid family which is relevant for this component is shown in Figure 3.
Thus, the three branches stemming out of the aggregator perform the following functions:

1. Offer flexible tariffs including critical peak pricing and real-time pricing.

2. Two-way communications allow for pricing information to be transmitted to customers based on price changes each day and at timed intervals, determined by software at the enterprise level to allow real time or day ahead management.

3. Exception pricing as well as price changes associated with system emergency conditions and quantity available to enable the customer to either buy or sell depending on their capacity.

From this we can break down behaviour as shown in Figure 4 highlighting the behaviour of the system when supply of electricity is high, represented as:

$$\text{DRH} := \{\text{High Supply, Agreement, Sell, Equilibrium}\}$$

This means that when the utility has excess supply of electricity, it will take advantage of existing agreements with their customers to sell and allow the system to get back to a state of equilibrium.

![Figure 4: A behavioural description of demand response when supply is high](image)

### 4.2 Encoding the Product Line in Orc

The product demand response is realized in terms of service orchestration using the combinators as follows. From Figure 3 we model the two branches on the right. We need to spawn two independent threads at a point in the computation in this case depending on whether we are load shifting or executing an existing agreement and resume the computation after both threads at the equilibrium point. Therefore,
we call sites (`real_time | day_ahead`) and (`sell | buy`) in parallel and compose using the asymmetric parallel combinator. The call then publishes the values as a tuple after they both complete their executions.

\[ DR := \text{let } (u,v) < \text{Load\_shift} < (\text{real\_time | day\_ahead}) < \text{Agreement} < (\text{sell | buy}) \]

The values published by this expression are the values contained in site `let`, which acts as a container for the first result published and releases both when the second value is received.

In the same way we can model the fact that these two features are alternatives. This means that once we instantiate the computation `Load\_shift` we are not in a position to execute `Agreement` and vice versa. We therefore have

\[ (\text{if}(f) \gg \text{L}_s) | (\text{if}(\neg f)) \gg A \ll f \in ((\text{real\_time | day\_ahead}) \gg \text{let}(\text{true})) | ((\text{buy | sell}) \gg \text{let}(\text{false})) \]

in which, due to restrictions in space, we have used the following abbreviations: \( f \) for flag (our container for the computation published first), \( L_s \) for `Load\_shift` and \( A \) for `Agreement`. As a start, we call \( L_s \) and \( A \) in parallel by utilizing the independent parallel combinator and await for values published by either (`real\_time | day\_ahead`) or (`sell | buy`) to determine which of the computations is executed. The value published first by the asymmetric parallel combinator is held. The site `if` returns the value held in \( A \) if \( A \) is true, and otherwise does not respond and thus, completes the alternative service reasoning.

**Why Orc?** The dynamic nature of this illustration highlights the dynamic nature of the various components and services of the Smart Grid, which is the main reason why we opted to work on the Orc calculus. Dynamic service, market management and pricing are basic building blocks of a Smart Grid system while Orc allows for the dynamic combination of services and the dynamic reconfiguration of software systems. The idea of invoking a published service instead of developing an isolated function leads a revolution of application development [29]. Thus, electricity business jobs can be arranged by orchestrating the services which can provide computation resources or functional support.

### 4.3 Semantics

The semantics is operational, asynchronous, and based on LTSs [24]. We show what this means for our case study. We have \(?k\), which denotes an instance of a site call that has not yet returned a value, where \( k \) is a unique handle that identifies the call instance. The transition relation \( A \xrightarrow{a} A \), states that expression \( A \) may transition with event \( a \) to expression \( A \). There are four kinds of events, which we call base events:

\[ a, b \in \text{BaseEvent} ::= !v \mid \tau \mid M_k(v) \mid k?v \]

A publication event, \(!v\), publishes a value \( v \) from an expression. As is traditional, \( \tau \) denotes an internal event. The remaining two events, the site call event \( M_k(v) \) and the response event \( k?v \), are discussed below.

A site call \( M(v) \), in which \( v \) is a value, transitions to \(?k\) with event \( M_k(v) \). The handle \( k \) connects a site call to a site return — a fresh handle is created for each call to identify that call instance. The resulting expression, \(?k\), represents a process that is blocked waiting for the response from the call. A site call occurs only when its parameters are values; in \( M(x) \), in which \( x \) is a variable, the call is blocked until \( x \) is defined.

The composition rules are straightforward, except in some cases in which subexpressions publish values.
Consider the independent parallel combinator ($A | B$). When $A$ publishes a value ($A \xrightarrow{!v} A$), it creates a new instance of the right-hand side, $[v/x].B$, the expression in which all free occurrences of $x$ in $B$ are replaced by $v$. The publication $!v$ is hidden, and the entire expression performs a $\tau$ action. Note that $A$ and all instances of $B$ are executed in parallel. Since the semantics is asynchronous, there is no guarantee that the values published by the first instance will precede the values of later instances. Instead, the values produced by all instances of $B$ are interleaved arbitrarily.

Asymmetric parallel composition, ($A <x< B$), is similar to parallel composition, except when $B$ publishes a value $v$. In this case, $B$ terminates and $x$ is bound to $v$ in $A$. One subtlety of these rules is that $A$ may contain both active and blocked subprocesses — any site call that uses $x$ is blocked until $B$ publishes.

We now check one of our expressions:

$$DR := \text{let } (u, v) < \text{Load shift} < (\text{real time} \mid \text{day ahead}) < \text{Agreement} < (\text{sell} \mid \text{buy})$$

An execution of $DR$ is as follows: the first step ($\text{sell} \mid \text{buy}$) publishes $\text{sell}$ or $\text{buy}$, which is bound to $\text{Agreement}$:

$$[\text{sell}/\text{Agreement}],(\text{sell} \mid \text{buy})$$

or

$$[\text{buy}/\text{Agreement}],(\text{sell} \mid \text{buy})$$

The same strategy is employed for the next step and we have an event $\tau$ due to the site $\text{let}$ as it receives one value before the other.

5 Conclusion and Future work

Correct modeling of service product lines appears to be important — if not vital — in order for them to provide the same level of accuracy and support as their earlier counterparts, service-oriented applications and SPLs. We have seen that Orc, being a language for orchestration at a moderately abstract level, provides important support for this. We have proposed that services can be modeled in a new way by incorporating variability notions from SPLs. It is perhaps unexpected how direct the resulting reasoning is to variability in product family descriptions using feature modeling. This is due to the extent to which Orc captures the sequences of publications.

We have not fully formalized service product lines, but the techniques and tools identified and the relationships established amongst them are a firm foundation for this. We plan to extend Orc in order to support the abstract layer provided by the MTSs and to allow verification by means of the $\nu$CTL logic. Feature models will remain our low-level representation of our service product lines. To fully formalize and verify service product lines, we require that Orc has the capability to integrate the tools. We also intend to extend the LTS-based semantics of Orc to an MTS-based semantics in order to utilize the $\nu$CTL logic for verification.

Acknowledgments

We thank the referees and participants of WWV 2011 for their useful comments before, during and after the workshop, which have considerably improved this paper.
References


